

NPTEL Video Lecture Topic List - Created by LinuXpert Systems, Chennai

NPTEL Video Course - Electrical Engineering - Optimal Control

Subject Co-ordinator - Prof. G.D. Ray

Co-ordinating Institute - IIT - Kharagpur

Sub-Titles - Available / Unavailable | MP3 Audio Lectures - Available / Unavailable

- Lecture 1 - Introduction to Optimization Problem
- Lecture 2 - Introduction to Optimization Problem
- Lecture 3 - Optimality Conditions for Function of Several Variables
- Lecture 4 - Optimality Conditions for Function of Several Variables (Continued.)
- Lecture 5 - Unconstrained Optimization Problem (Numerical Techniques)
- Lecture 6 - Solution of Unconstrained Optimization Problem Using Conjugate Gradient Method and Networks Method
- Lecture 7 - Solution of Unconstrained Optimization Problem Using Conjugate Gradient Method and Networks Method
- Lecture 8 - Solution of Constraint Optimization Problem-Karush-Kuhn Tucker (KKT) Conditions
- Lecture 9 - Solution of Constraint Optimization Problem-Karush-Kuhn Tucker (KKT) Conditions (Continued.)
- Lecture 10 - Problem and Solution Session
- Lecture 11 - Post Optimality Analysis, Convex Function and its Properties
- Lecture 12 - Post Optimality Analysis, Convex Function and its Properties (Continued.)
- Lecture 13 - Quadratic Optimization Problem Using Linear Programming
- Lecture 14 - Matrix form of the Simplex Method
- Lecture 15 - Matrix form of the Simplex Method (Continued.)
- Lecture 16 - Solution of Linear Programming Using Simplex Method
- Lecture 17 - Solution of Linear Programming Using Simplex Method
- Lecture 18 - Solution of LP Problems with Two Phase Method
- Lecture 19 - Solution of LP Problems with Two Phase Method (Continued.)
- Lecture 20 - Standard Primal and Dual Problems
- Lecture 21 - Relationship Between Primal and Dual Variables
- Lecture 22 - Solution of Quadratic Programming Problem Using Simplex Method
- Lecture 23 - Interior Point Method for Solving Optimization Problems
- Lecture 24 - Interior Point Method for Solving Optimization Problems (Continued.)
- Lecture 25 - Solution of Nonlinear Programming Problem Using Exterior Penalty Function Method
- Lecture 26 - Solution of Nonlinear Programming Problem Using Exterior Penalty Function Method (Continued.)
- Lecture 27 - Solution of Nonlinear Programming Problem Using Interior Penalty Function Method
- Lecture 28 - Solution of Nonlinear Programming Problem Using Interior Penalty Function Method (Continued.)
- Lecture 29 - Multiobjective Optimization Problem

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- Lecture 30 - Dynamic Optimization Problem
- Lecture 31 - Dynamic Optimization Problem
- Lecture 32 - Dynamic Optimization Problem
- Lecture 33 - Numerical Example and Solution of Optimal Control Problem using Calculus of Variation principle
- Lecture 34 - Numerical Example and Solution of Optimal Control Problem using Calculus of Variation principle
- Lecture 35 - Hamiltonian Formulation for solution of optimal Control problem and numerical example
- Lecture 36 - Hamiltonian Formulation for solution of optimal Control problem and numerical example (Continued)
- Lecture 37 - Performance Indices and Linear Quadratic Regulator Problem
- Lecture 38 - Performance Indices and Linear Quadratic Regulator Problem (Continued.)
- Lecture 39 - Solution and Stability Analysis of Finite - time LQR Problem
- Lecture 40 - Solution and Infinite - time LQR Problem and Stability Analysis
- Lecture 41 - Numerical Example and Methods for Solution of A.R.E.
- Lecture 42 - Numerical Example and Methods for Solution of A.R.E. (Continued.)
- Lecture 43 - Frequency Domain Interpretation of LQR Controlled System
- Lecture 44 - Gain and Phase Margin of LQR Controlled System
- Lecture 45 - The Linear Quadratic Gaussian Problem
- Lecture 46 - Loop-Transfer Recovery
- Lecture 47 - Dynamic Programming for Discrete Time Systems
- Lecture 48 - Minimum \hat{a} Time Control of a Linear Time Invariant System
- Lecture 49 - Solution of Minimum \hat{a} Time Control Problem with an Example
- Lecture 50 - Constraint in Control Inputs and State Variables
- Lecture 51 - Constraint in Control Inputs and State Variables (Continued...)
- Lecture 52 - Norms for Vectors, Matrices, Signals and Linear Systems
- Lecture 53 - Signal and System Norms
- Lecture 54 - Internal Stability, Sensitivity and Complementary Sensitivity Functions
- Lecture 55 - Internal Stability, Sensitivity and Complementary Sensitivity Functions (Continued...)
- Lecture 56 - Plant Uncertainty and Standard form for Robust Stability Analysis
- Lecture 57 - Plant Uncertainty and Standard form for Robust Stability Analysis (Continued...)
- Lecture 58 - Frequency Response of Linear System and Singular Value Decomposition of System
- Lecture 59 - Control Problem Statement in H- α Framework
- Lecture 60 - Control Problem Statement in H - α Framework (Continued...)