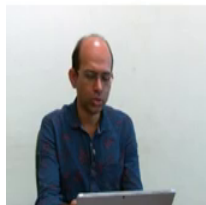


Introduction to Probabilistic Methods in PDE
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Lecture 15
Brownian motion as the building block

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- Multidimension Ito's formula:** Let M be a \mathbb{R}^d valued $\{\mathcal{F}_t\}$ adapted process in $\mathcal{M}^{c,loc}$. A is also \mathbb{R}^d valued adapted process of BV with $A_0 = 0$.
 Set $X_t = X_0 + M_t + A_t$, where $X_0 \in \mathbb{R}^d, \mathcal{F}_0$ measurable.
 If $f : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}$ is in $C^{1,2}$, then P a.s. $\forall t \geq 0$.

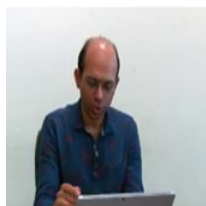
$$f(t, X_t) = f(0, X_0) + \int_0^t \frac{\partial}{\partial t} f(s, X_s) ds + \sum_{i=1}^d \int_0^t \frac{\partial}{\partial X_i} f(s, X_s) dA_s^i + \sum_{i=1}^d \int_0^t \frac{\partial f}{\partial x_i}(s, X_s) dM_s^i + \frac{1}{2} \sum_i \sum_j \frac{\partial^2}{\partial x_i \partial x_j} f(s, X_s) d\langle M^i, M^j \rangle_t$$



- Integration by parts formula:** Consider two semi-martingales $X (= X_0 + M + B)$ and $Y (= Y_0 + N + C)$ where M and N are in $\mathcal{M}^{c,loc}$ and B, C are continuous BV with $B_0 = C_0 = 0$. Then

$$X_t Y_t = X_0 Y_0 + \int_0^t X_s dY_s + \int_0^t Y_s dX_s + \langle M, N \rangle_t$$

- Levy's Martingale characterisation of Brownian motion:**
 Let X be continuous \mathbb{R}^d valued adapted to $\{\mathcal{F}_t\}$ s.t.
 $M_t^k = X_t^{(k)} - X_0^k$ is a continuous local martingale and
 $\langle M^{(i)}, M^{(j)} \rangle_t = \delta_{i,j} t \forall 1 \leq i, j \leq d$.
 Then X is a d -dimensional Brownian motion.



So, now we would see some generalization of Ito's formula. We are not going to prove these results. We are going to state these results, which is immediate, immediate in the sense that exactly the similar techniques is required. This is just multidimensional version of that.

So, imagine that your X semi martingale is not a real valued but Euclidean space valued. So imagine, so let us start reading from here. So let, M be a \mathbb{R}^d valued, Euclidean space valued \mathcal{F}_t adapted process and that is continuous local martingale, and A is also \mathbb{R}^d valued, adapted process of bounded variation with A_0 is equal to 0, and if we add, you know M_t , A_t and some X_0 which is \mathcal{F}_0 measurable then what you are going to get is a semi martingale.

So, if we consider this semi martingale X_t and then you know, function f is just a function of time, earlier our function f was not explicitly dependent on time t , only dependent on the space X but here we allow f to be a function of time and also function of X_t , X_t is coming from \mathbb{R}^d so it is, the domain is close 0 to open infinity and cross \mathbb{R}^d , Cartesian product of these two sets. And we need to assume some kind of, you know differentiability of f , otherwise we cannot write down the Ito's formula. Here we consider f to be $C^{1,2}$, 1 means it is once differentiable with respect to time, and twice differentiable with respect to space.

Then, the statement of the theorem says that with probability 1 for all t we are going to get this value. What is this equal to, left hand side you have f of t , X_t and then right hand side you have, this is the value of f evaluated at time 0 and the process also at 0, so starting point, so value of function at 0.

And then we have some other integral terms, first term is the first order derivative of f with respect to the first variable. So, $\frac{\partial}{\partial t} f$, denotes the first order derivative of f with respect to the first variable, where that function is evaluated at point s , X_s and then this becomes a function of S , and you integrate that with respect to s from 0 to t . So, then you get a process, by varying t you are going to get a various different random variables, you are going to get a stochastic process with respect to time t .

And then this term is, the first order derivative of f with respect to second variable; second variable is multidimensional, it has d number of components. So, one needs to take the gradient from here, like you know one has to take all the derivatives. So, we take sum of that i is equal to 1 to d $\frac{\partial}{\partial X_i} f$ of s , X_s , X_i is, stands for, actually I wanted to write the small x , this is typo, so $\frac{\partial}{\partial x_i}$ stands for, derivative of f with respect to the i th component

of space variable, and then integrate with respect to the boundary variation processes, I mean that is also part of the Ito's formula which we see that , with respect to the bound variation process and with respect to the local martingale process.

So, this is the only new term we are seeing here because we have taken f to be a function which depends on time explicitly, so that is why you are getting this extra term. And here, so this is integration with respect to A_s , and this part is the stochastic integration of $\text{del} f \text{ del} x_i$ with respect to M_i , and then there is a remaining term that is, there is a typo, this will be small s here, so this is summation half times, summation over all possible i and j $\text{del}^2 \text{ del} x_i \text{ del} x_j$, f of s , X_s , then quadratic covariation of M_i and M_k , $d M_i M_j s$. And then, I think integration sign is also missing, there should be integration sign here 0 to t . So, this is the multidimensional Ito's formula.

So, there is another important result. So, this is integration by parts formula. Consider two semi martingales, X and Y . X is having the decomposition X_0 plus M plus B , where Y is having the decomposition Y_0 plus N plus C , where M and N are continuous local martingales, and B and C are adapted boundary variation processes, and then B_0 is equal to C_0 is equal to 0 . So, these are the two semi martingales.

Then we know that, product of X and Y , $X_t Y_t$ is equal to $X_0 Y_0$ plus integration 0 to t $X_s dY_s$ plus integration 0 to t $Y_s dX_s$ plus the quadratic covariation of M and N , at time t , so that appears. So, this is the integration by parts formula. Actually, if you compare this formula with the classical calculus by parts formula, you would get all these terms except this one.

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• **Levy's Martingale characterisation of Brownian motion:**

Let X be continuous \mathbb{R}^d valued adapted to $\{F_t\}$ s.t.

$M_t^k = X_t^{(k)} - X_0^k$ is a continuous local martingale and

$\langle M^{(i)}, M^{(j)} \rangle_t = \delta_{ij}t \forall 1 \leq i, j \leq d$.

Then X is a d -dimensional Brownian motion.

• Suppose $M = \{M_t\}_{t=0}$ is defined on (Ω, \mathcal{F}, P) with

$M^{(i)} \in \mathcal{M}^{c,loc} \forall i = 1, \dots, d$.

Suppose also that for each pair $1 \leq i, j \leq d$, the $\langle M^{(i)}, M^{(j)} \rangle$ is absolutely continuous w.r.t. $t [P]$ a.s.

Then there is an extension $(\tilde{\Omega}, \tilde{\mathcal{F}}, \tilde{P})$ of (Ω, \mathcal{F}, P) on which is defined a d -dimensional Brownian motion $W = \{W_t\}_{t \geq 0}$ and a matrix $X \in \mathcal{P}(W)$, under \tilde{P} , i.e. measurable and adapted

process with $\tilde{P} \left(\int_0^t (X_s^{(i,k)})^2 ds < \infty \right) = 1 \forall i, k, t$ s.t.



$$M_t^{(i)} = \sum_{k=1}^d \int_0^t X_s^{(i,k)} dW_s^{(k)}, \langle M^{(i)}, M^{(j)} \rangle_t = \sum_{k=1}^d \int_0^t X_s^{(i,k)} X_s^{(j,k)} ds.$$

So, this is also one very important result but this result is related to one property of Brownian motion that, Brownian motion has quadratic variation as identity function. What does it mean, that quadratic variation process of B , by B is a Brownian motion, quadratic variation process of B is nothing but the time itself. So, we are going to see the detailed proof of that in another class.

So, here for the time being we assume that result. So, for explanation, you can see that this result is actually saying that the reverse is also true. What is the reverse statement of that, that let X be continuous \mathbb{R}^d valued adapted F_t process, such that difference of the process with the initial value so that you get another process which starts from 0. I mean just for the sake of starting from 0, we just subtract the process by its, I mean subtracted the initial point from the process, so the initial value becomes 0.

Now this Mkt, if that is a continuous local martingale and its components, it has, it is vector correct, it has d number of components so, and for every components, i , and pair of components i and j , the quadratic covariation is $\delta_{ij}t$. If that is the case then what can we say, that if i is not equals to j , then δ_{ij} would be 0, so the quadratic variation will be 0. If i is equal to j , then M_i and pair, actually, the same thing, so this is actually quadratic variation of the i th component of the vector and that is exactly t .

So, imagine that we have one such local martingale X , such that M_k which is you know centralized, for that we have this particular property. If that is a case, then X is a

d-dimensional Brownian motion. This is called Levy's Martingale characterization of Brownian motion. Brownian motion is the only process which has this property, mindfully continuous is very important..

There could be some other local martingales which is not continuous and not Brownian motion but having the same property. But for continuous local martingale this Brownian motion is the only member which has this property, that quadratic variation of one-dimensional Brownian motion is just the time itself.

Suppose, M is a stochastic process defined on the probability space $\omega, \mathcal{F}, \mathbb{P}$ with each and every component M_i , is continuous local martingale. And suppose, we have that quadratic covariation of M_i and M_j , is absolutely continuous with respect to t . So, here we are considering a larger class. We saying that, okay it is not exactly t but it is absolutely continuous with respect to t .

What does it mean, it means that we can actually, I mean if we take one interval where there this quadratic covariation, which is increasing process, that increasing process, the difference would be made smaller and smaller if we make the increment of the time smaller and smaller. And I mean in the sense that, I mean, if I take a finitely, you know finite union of intervals with measure δ , sum of the length is δ , does not matter where are these, you know intervals located.

So, I can always find out one small random variable ϵ such that, we can, that, given ϵ I can always find out small δ such that whenever these, you know small sum of the intervals of the time is, size is less than δ , the difference, corresponding difference of increments would also be less than ϵ .

So, that is the meaning of this, this is basically absolutely, continuous with respect to t is same as saying this is just absolutely continuous, this is absolutely continuous. Then, there is an extension.

This extension in which sense, that, like you know, we can augment Ω to make a larger Ω and then correspondingly we have to increase, you know, we have to change the sigma algebra, and also the probability measure. But it is possible, it is possible to, you know extend the probability space, such that on which we can define a d-dimensional Brownian motion W , and a matrix X which is in the $\mathcal{P}(W)$ class.

What is $\mathcal{P}(W)$, $\mathcal{P}(M)$ class we have already seen. That you know, it is progressively measurable, I mean, not progressively measurable, that is \mathcal{P}^* . \mathcal{P} class is just the adapted and this probability of the integration with respect to the quadratic variation, here quadratic variation of W is just time, is finite, that probability is 1.

So, what is the conclusion, conclusion is that for such process M , we can find out a larger probability space on which you can construct a Brownian motion W . And one process, one matrix valued process X , such that this M can be written as integration of X with respect to W .

So, M can be written as, I mean here we cannot claim M is exactly W , earlier as we have done but here because you know, here quadratic variation is not, there is a typo, there should be, the right angle notation So, because quadratic variation of this is just absolutely continuous with respect to t , but using that thing one can construct this you know, integrand X , a matrix, and this vector W , you know this Brownian motion, d-dimensional Brownian motion.

And then this integration has a proper meaning. that matrix and the vector, so you are going to get a vector in d-dimensional process only, and that d-dimensional process is going to coincide with M_t . So, this matrix multiplication is here written in this manner, k is equal to 1 to t , $X_{ik} dW_k$. This is nothing but the matrix multiplication. This is matrix, this is a vector, and 0 to t , here I should have written 0 to t .

So, that is, basically saying that, does not matter what is your martingale, as long as your martingale's quadratic variation process is an absolutely continuous process. Then that M_c

loc, that you know M is not even martingale, just a local martingale. Then that local martingale M_t can be written as integration of a matrix, adapted and which is in the P W class, matrix with d -dimensional Brownian motion.

That means we can represent that martingale in terms of Brownian motion, basically. So, that actually tells the Brownian motion is actually building blocks of the stochastic processes, as long as you are dealing with the cases where the quadratic variation is absolutely continuous process.

And also the formula we see now, that if we look at the quadratic covariation of the i th and j th component of this local martingale, that can also be written in terms of this matrix X , that $X_{ik} X_{jk}$ and sum over k is equal to 1 to d , so what you are going to get is that this ds , so this is the matrix, correct for i, j . So you also are going to get, this is matrix multiplication. So, you are going to get this matrix and this matrix you are just taking integration, 0 to t , so you are going to get this matrix, M_{ij} .

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• **Time change for martingales:** [Dambis (1965), Dubin and Schwarz (1965)]

Let $M = \{M_t\}_{t \geq 0} \in \mathcal{M}^{c,loc}$ satisfy $\lim_{t \rightarrow \infty} \langle M \rangle_t = \infty$ a.s.

Define for each s

$$T(s) := \inf\{u : \langle M \rangle_u > s\}$$

$$\{\omega | T(s) < t\} = \{\omega | \langle M \rangle_t(\omega) > s\} \in \mathcal{F}_t$$

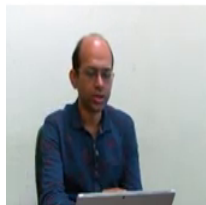
Hence, $T(s)$ is $\{\mathcal{F}_t\}$ stopping time $\forall s > 0$.

The time changed process $B := \{B_s\}_{s \geq 0}$

given by $B_s := M_{T(s)}$ and $\mathcal{G}_s := \mathcal{F}_{T(s)}$

is the $\{\mathcal{G}_s\}$ -adapted 1-dimensional Brownian motion.

Also $M_t = B_{\langle M \rangle_t} \forall t \geq 0$ a.s. [P].



So, this is time change for martingale. This is another way, of viewing Brownian motion as building block, another way. So, what is this? this is the work of Dambis in 1965, Dubin, Schwarz in 1965. This is quite old work.

So, this says that when M is a continuous local martingale and which satisfies this particular condition, so this is just saying that it is not converging to a finite number.

So, as t tends to infinity, quadratic variation of M_t is going to infinity, I mean, Brownian motion has that of course, and which process does not have that. For example, you take an arbitrary local martingale and then you consider a stopped process, localization where using a stopping time, which is the hitting time of a boundary of some kind of big ball.

So, then that would be like, you know, does not matter what t is, this would be bounded, it is fixed, it would not go to infinity. So, only thing is that you should, I mean if we do not consider that type of processes. So, here the quadratic variation process grows to infinity. So, under this condition you can define this random variable T_s for each and every positive number s , such that this is infimum of u , such that quadratic variation of M_u is greater than s .

So, what does it do, this is actually some sort of generalized inverse, inverse of a function. If a function, you know μ is exactly a bijection, from close 0 to infinity, close 0 to infinity, then this would actually coincide with the M inverse.

However, sometimes you know, M may have a some kind of, may have constants. So, those kinds of things, there you cannot talk about inverse but we can of course talk about this infimum, so when it crosses s for the first time, when it crosses s for the first time. So, that is called T_s . If you are finding this formula little, you know, non intuitive you can think just inverse of M , just generalized inverse of M . Also, we use like, you know percentile function for, you know inverting CDF etc. also in the same manner.

So, here this T_s , we first see that T_s is a, is an F_t stopping time. So, let us see, how to do that, this is actually very trivial. So, we considered this as event, set of the sample points, such that T_s of ω is less than t .

So, when T_s is less than t what does it mean, that before time t , that μ has crossed this, because μ , when μ crosses s for the first time that is T_s and T_s is less than t ; that means, I mean before t , T_s has crossed s . So, that means at t , M_t of course, has crossed because M_t is increasing process. The quadratic variation process is increasing process.

So, M_t , so this is same as, I mean, actually first you get that this is a subset of that, because this implies this and the reverse also, is also you can expect, so this is equal, these two events are equal. And here, if you look at this event, what is there, this is that M_t is F_t measurable, and then we are asking that, the set of events under which M_t is more than s , s is some fixed real number. So, that event is of course, in the same sigma algebra F_t . So therefore, this is in F_t .

So, we have therefore shown that this is true, capital T_s is, capital T_s is less than t , that event is in F_t for every t positive. So, that in turns says that capital T_s is in F_t stopping time. Now, we have a family of stopping times. For each and every s we have a stopping time, T_s is family stopping time.

Now we consider, the time changed process B , so B is the process B_s , where B_s is given by this. What is this, B_s is defined as capital M evaluated at time capital T of s . So, now this is important. You can think that, T_s is the inverse of quadratic variation of M , and then if you put small t here, this T_s equals small t , then s would be that quadratic variation at t , because this is the inverse.

So, t inverse would be M_s , so B M_s , I mean quadratic variation of M_s would be M_s . So, that we are going to get here, that M_t is equal to B quadratic variation of t . Now what would be the, what should be the measurability of B , that, for that we have to change the filtration also, depending upon, because now time has changed, right therefore filtration should also change.

So, we are going to take F subscript T_s . So, because this is a stopping time, so for this particular stopping time we have stopped sigma algebra and as s is increasing T_s is also non decreasing process. So, this would give me another filtration, coming from the stop sigma algebra. And if you call this as the filtration G_s , so this B_s is G_s adapted, and this is also Brownian motion.

This is a Brownian motion and this Brownian motion, it has this property, that BM this t is equal to M_t . And now, you can actually take quadratic variation of this thing, so quadratic variation of this process B_t on the right hand side, and left hand side going to M_t , you are going to see that, that thing would match with this value. So basically, from here one can easily find out this is Brownian motion. If you can show this, the quadratic variation of this would be exactly, would match, this would match.

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- If $X = \{X_t\}_{t \geq 0}$ is progressively measurable and

$$\int_0^\infty X_t^2 d\langle M \rangle_t < \infty \text{ a.s.}$$

Then $Y_s := X_{T(s)}$ is adapted to $\{\mathcal{G}_s\}$ and a.s.

- $\int_0^\infty Y_s^2 ds < \infty$

- $\int_0^t X_v dM_v \leq \int_0^{(M)_t} Y_u dB_u$ for all $t \geq 0$

- $\int_0^{T(s)} X_v dM_v = \int_0^s Y_u dB_u$ for all $s \geq 0$.



- **Time change for martingales:** [Dambis (1965), Dubin and Schwarz (1965)]

Let $M = \{M_t\}_{t \geq 0} \in \mathcal{M}^{c,loc}$ satisfy $\lim_{t \rightarrow \infty} \langle M \rangle_t = \infty$ a.s.

Define for each s

$$T(s) := \inf\{u : \langle M \rangle_u > s\}$$

$$\{\omega | T(s) < t\} = \{\omega | \langle M \rangle_t(\omega) > s\} \in \mathcal{F}_t$$

Hence, $T(s)$ is $\{\mathcal{F}_t\}$ stopping time $\forall s > 0$.

The time changed process $B := \{B_s\}_{s \geq 0}$

given by $B_s := M_{T(s)}$ and $\mathcal{G}_s := \mathcal{F}_{T(s)}$ is the $\{\mathcal{G}_s\}$ -adapted 1-dimensional Brownian motion.

Also $M_t = B_{\langle M \rangle_t} \forall t \geq 0$ a.s. [P].



So, this is the last slide, so fifth one, sixth point. If X is progressively measurable, so X is equal to measurable process such that, this is actually, I mean P star of M basically, that probability of integration 0 to infinity X_t square d you know, quadratic variation M_t is finite with probability 1 and is progressively measurable. Then, Y defined as time change process of X , X subscript capital T_s is adapted to \mathcal{G}_s because you know the time change, since you have to change the time, so we have to change the filtration also, is adapted to the \mathcal{G}_s filtration and almost surely, we have following properties.

So here, this is not very surprising. Let me explain why, because you know, this X_t square integration 0 to t dM_t is finite with probability 1. So, if we can, you know take control of this thing then X_t square is not growing much. So here, X_t is Y_s , so Y_s square is like the time

when you know M_t , you know just crosses s . So, that thing is there, so for a fixed s . And then we are considering s running from 0 to infinity, that is finite.

This is like a time change formula, and here we have integration of $X dM$, for example you consider. And now, we apply the time change formula. So here, if we replace v by T_s you know so here, like T_s is there, so if we replace this by T_s . So, then we are going to get, for X also T_s is Y_s , so instead of that I am going to get Y_s here, instead of M_t I am going to get the Brownian motion here, and then instead of small t , we are going to get the quadratic variation of M at t .

There is one more identity. So, this identity is saying that, here we had 0 to t , instead of that here if we have integration 0 to capital T_s , but integrand and integrators are same, there the limit has changed. So then, for small t we have got, the quadratic variation of M and this is like inverse of that, so we are going to get this s here, correct, s here. So here, all others are same, for all s greater than or equal to 0. Thank you very much.