

STOCHASTIC APPROXIMATION: THEORY AND APPLICATIONS

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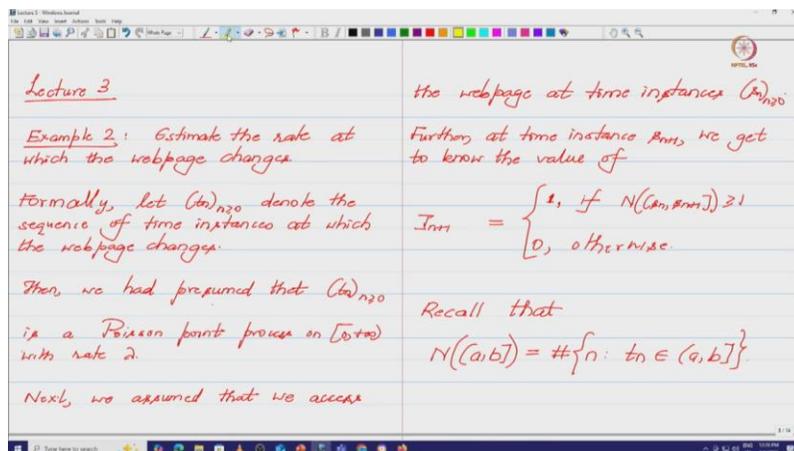
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Lecture 3

Estimating change rates of webpages

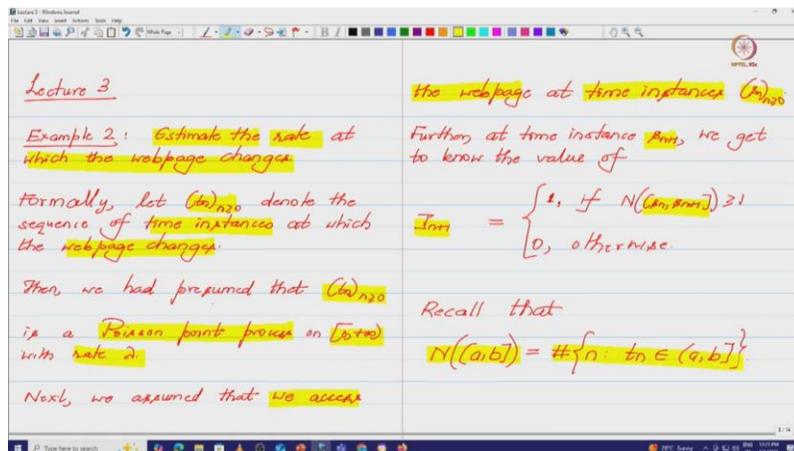
Hello and Namaste, everyone. Welcome to Lecture 3. Let us do a quick recap of what we have covered in Lectures 1 and 2. In Lecture 1, we discussed an example of stochastic approximation, which involved estimating the mean of a random vector X using samples of the same random vector X . Then, in Lecture 2, we began looking at a more realistic setup where the goal was to estimate the expected value of some random vector X using samples of another random vector Y .



More specifically, we looked at the problem of estimating the rate at which the web page changes. So, this was the problem that we considered. And formally, we described this problem in the following way. We presume that T_n , the sequence T_n —that means T_0, T_1, T_2, T_3 , and so on and so forth—denotes the time instances at which the web page changes. And then, for simplicity, we had presumed that this sequence forms a Poisson point process on the positive or non-negative real line with rate λ .

And I had told you that the sequence T_n is said to be a Poisson point process if the interarrival times—that is, T_{n+1} minus T_n —for different values of n , form a sequence of independent and identically distributed exponential random variables with parameter λ . Right. And then we said that we don't have direct access to the times at which the web page changes. Instead, we said that often we may only be able to access the web page at time instances S_N . Right, and at time instance S_{N+1} , we only get to know if the web page has changed in the interval S_N to S_{N+1} .

in particular, at time instance S_N plus 1, we said that we have access to the value of the random variable I_{N+1} which is a 0/1 random variable, 0, if the web page has not changed between S_N and S_N plus 1 and 1, if it has changed at least once. So, recall that $N(a,b)$ equals the number of values in the set described over here. So, this set includes all those values of n where t_n lies between a and b . So, $n(a,b)$ is the cardinality of this set, and I denote cardinality by this hash variable, right?



So, this is what I use over here, this definition is what I use over here, right? And notice that S_n , S_n plus 1, these are all random variables, right? And n of S_n comma S_n plus 1 is another random variable, right? So, now our formal question is, can we estimate λ which denotes the rate at which the web page changes using values of the 0/1 random variables i_1 , i_2 , i_3 and so on and so forth. So, let us get a pictorial view of this problem.

Thus, the formal question is can we estimate λ using the value of the O/I random variables I_1, I_2, I_3, \dots .

Pictorially, the setting can be viewed as follows.

Mathematical Formulation:
 Suppose $(S_n)_{n \geq 0}$ is a Poisson point process with known rate λ .

We now understand properties of the sequence $(I_n)_{n \geq 0}$.

The diagram shows a horizontal axis with blue circles labeled S_0, S_1, S_2, S_3, S_4 and red crosses labeled $t_0, t_1, t_2, t_3, t_4, t_5$. Below the axis, intervals are labeled $I_1=0, I_2=1, I_3=1, I_4=1$.

So, imagine this black line to denote the time axis and the red crosses. So, you can see that there are a bunch of red crosses. So, let us presume that these red crosses denote the times at which the web page changes. So, you can see that you know, so t_0 is basically some initial point of convenience. So, do not read too much into T_0 , we will presume that T_0 is 0, right.

So, T_1 is the first time at which the web page changes from this chosen time of reference. T_2 is the second time instance at which the web page changes. We can have similar interpretations for T_3, T_4 , and T_5 . Notice that the distance between T_0 to T_1, T_1 to T_2, T_2 to T_3 is not the same. This is on purpose because, recall that if T_0, T_1, T_2, T_3 , and so on form a Poisson point process.

Then the interarrival times—that is, T_1 minus T_0, T_2 minus T_1 , and so on—are themselves exponential random variables, right? And because they are random variables, the width of these intervals will be different, and each time you repeat this experiment, the positions of T_0, T_1, T_2, T_3 , and so on will differ. For this particular instance of the experiment, let us presume that the places where I have put crosses are the times at which the web page changes. On the other hand, we have the time instances denoted by these blue circles at which we access the web page. So again, for convenience, we say that S_0 is 0, and that matches T_0 .

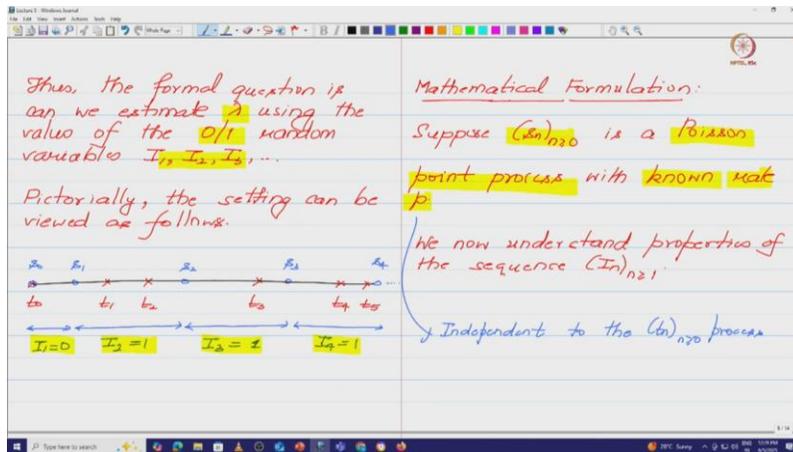
So, from this reference time, we access this web page at times S_1, S_2, S_3 , and so on. And again, we can presume that S_1 minus S_0, S_2 minus S_1 , and so on are regularly spaced. Recall that S_0, S_1, S_2 , and so on are under our control because we are designing a web

crawler that visits this web page. So, we are designing this crawler, and we can choose how often it visits this web page—whether at periodic intervals or at random instances of time—all of which is under our control. On the other hand, T_0, T_1, T_2, T_3 , and so on are not under our control; those are the times at which the web page changes, which is beyond our control.

But S_0, S_1, S_2, S_3 , and so on, they are indeed under our control, right? Now, as I told you, I_1 is the 0-1 random variable which tells us whether the web page has changed between S_0 and S_1 . Now, in this case, you can see that there is no cross which is strictly bigger than S_0 and less than or equal to S_1 , and that is the reason I_1 is 0. On the other hand, I_2 looks at whether the web page has changed between S_1 and S_2 , and you can see that there are two crosses between S_1 and S_2 , which means the web page changed twice. But I_2 will only be 1 because we will look at the copy of the webpage at time instance S_2 and compare it with the copy of the webpage that we had accessed at time instance S_1 , and we will only see that the webpage has changed.

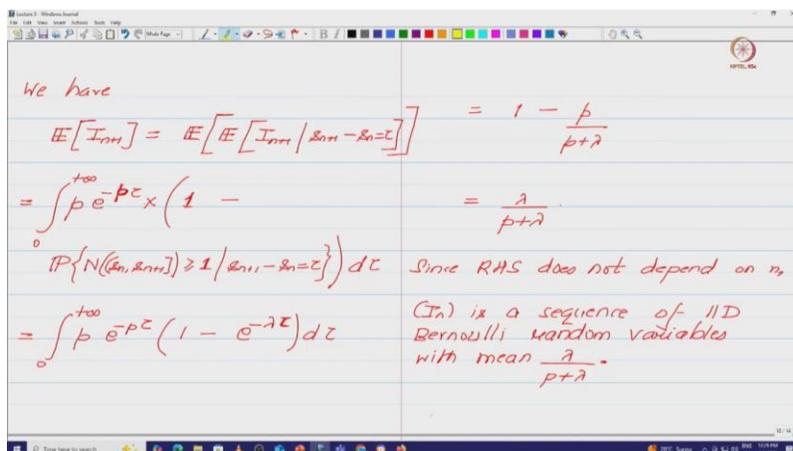
Because of this reason, this I_2 will only be 1 and not 2. And similarly, I_3 is 1 because there is exactly one time instance between S_2 and S_3 , which is T_3 , at which the web page changed. On the other hand, between S_3 and S_4 , there are two time instances at which the web page changed; hence, I_4 is again 1. So, the question is, given the values of $I_1, I_2, I_3 \dots$ which, again, notice that arrive sequentially—can we come up with a stochastic approximation algorithm to estimate λ , right? Now, as I told you, the time instances at which we visit this web page are under our control, so we could choose them to be regularly placed.

However, for ease of analysis, we will presume that S_N —that is, the sequence S_N , which is the time instances at which we access the web page—is actually another Poisson point process. But we will presume that this is a Poisson point process with a known rate P . So, we will presume that, and I should add that this process—sorry. I should add that this process—we will presume—is independent of the T_N process. So, now, under this assumption, our goal is to estimate λ .



So, before we discuss the algorithm to estimate lambda, what we will do is first estimate or first understand the properties of the sequence I_n . So, we will do that now. So, recall that I_n is actually a 0-1 Bernoulli random variable. So, let us try to compute its expected value. Now, by the properties of iterated expectation, one knows that the expected value of I_n plus 1 is the expectation of the expectation of I_n plus 1 under the condition that s_{n+1} minus s_n equals τ .

$$\mathbb{E}[I_{n+1}] = \mathbb{E}[\mathbb{E}[I_{n+1} | s_{n+1} - s_n = \tau]]$$



So, recall that s_{n+1} minus s_n , because of our choice that the sequence s_n is a Poisson point process with rate lambda, s_{n+1} minus s_n will be exponential with rate p , right? The times at which the web page changes is a Poisson point process with an unknown rate lambda. However, the times at which we access the web page is a Poisson point process with rate P . Hence, s_{n+1} minus s_n is an exponential random variable with parameter

P. So, our goal is, given that $S_N + 1 - S_N$ equals T , what is the conditional expectation of $I_N + 1$?

Now, recall that $I_N + 1$. So, let me go to the previous slide to explain this. So, recall that $I_N + 1$ tells us how many times the web page changes between two successive visits, in particular between S_N and $S_N + 1$. And now, under this conditional expectation, what we are saying is that suppose this time interval is of length τ , okay? So, we are presuming that the length of time over here equals τ .

Given this information, you know, what is the expected value of $I_N + 1$, which is equivalent to asking when $I_N + 1$ equals 1, because $I_N + 1$ is a Bernoulli random variable, right? So, we want to compute the expected value of $I_N + 1$, and from the basic properties of expectation, we know that the expected value of $I_N + 1$ can be written using the iterated expectation property, that is, the expectation of the expectation of $I_N + 1$ given $S_N + 1 - S_N = \tau$.

$$\mathbb{E}[I_{n+1} | s_{n+1} - s_n = \tau]$$

Now, recall that because the times at which we access the web page form a Poisson point process with a known rate P , this $S_N + 1 - S_N$ —sorry, this $S_N + 1 - S_N$ —would actually be an exponential random variable with rate P , right? And now, let me tell you how to find this expectation. So, I have given you the expression over here.

Thus, the formal question is can we estimate I_n using the value of the O/I random variables I_1, I_2, I_3, \dots

Pictorially, the setting can be viewed as follows.

length = τ

s_0 s_1 s_2 s_3

t_0 t_1 t_2 t_3 t_4 t_5

$I_1=0$ $I_2=1$ $I_3=2$ $I_4=1$

$\mathbb{E}[I_{n+1} | s_{n+1} - s_n = \tau]$

Mathematical Formulation:

Suppose $(s_n)_{n \geq 0}$ is a Poisson point process with known rate P .

We now understand properties of the sequence

Independent $(s_n)_{n \geq 0}$ process

We have

$$\mathbb{E}[I_{n+1}] = \mathbb{E}\left[\mathbb{E}[I_{n+1} | s_{n+1} - s_n = \tau]\right] = 1 - \frac{p}{p+\lambda}$$

$$= \int_0^{\infty} p e^{-p\tau} \times \left(1 - \mathbb{P}\{N(s_{n+1}, s_n) = 0 | s_{n+1} - s_n = \tau\}\right) d\tau = \frac{\lambda}{p+\lambda}$$

$$= \int_0^{\infty} p e^{-p\tau} (1 - e^{-\lambda\tau}) d\tau$$

Since RHS does not depend on n

(I_n) is a sequence of IID Bernoulli random variables with mean λ

So, the outer expectation basically figures out what the probability is that $S_{n+1} - S_n$ takes the value τ in a small interval. So, this is given over here—this times $d\tau$ —and this inner conditional expectation is given in this round bracket. So, let me now explain how this inner conditional expectation is found. So, the inner conditional expectation—because your I_{n+1} is a Bernoulli random variable—actually equals the conditional probability that I_{n+1} equals 1, given $S_{n+1} - S_n$ equals τ .

Now, this probability equals 1 minus the probability that I_{n+1} equals 0 with the same conditioning. The same conditioning that we have over here—place it over here. Now, I_{n+1} is 0 if and only if there are no changes in the interval starting from S_n and ending at S_{n+1} . So, that is what I have written over here. So, this probability and this probability are one and the same.

$$\begin{aligned} \mathbb{E}[I_{n+1} | s_{n+1} - s_n = \tau] &= \mathbb{P}\{I_{n+1} = 1 | s_{n+1} - s_n = \tau\} \\ &= 1 - \mathbb{P}\{I_{n+1} = 0 | s_{n+1} - s_n = \tau\} \end{aligned}$$

We have $E[I_{n+1} | s_{n+1} - s_n = z] = \mathbb{P}\{I_{n+1} = 1 | s_{n+1} - s_n = z\}$

$$E[I_{n+1}] = E\left[E[I_{n+1} | s_{n+1} - s_n = z]\right] = 1 - \frac{p}{p+\lambda}$$

$$= \int_0^{+\infty} p e^{-pz} \times \left(1 - \frac{p}{p+\lambda}\right) dz = \frac{\lambda}{p+\lambda}$$

$\mathbb{P}\{N((s_n, s_{n+1}]) = 0 | s_{n+1} - s_n = z\}$ Since RAS does not depend on s_n

(I_n) is a sequence of IID Bernoulli random variables with mean $\frac{\lambda}{p+\lambda}$

We have $E[I_{n+1} | s_{n+1} - s_n = z] = \mathbb{P}\{I_{n+1} = 1 | s_{n+1} - s_n = z\} = 1 - \mathbb{P}\{I_{n+1} = 0\}$

$$E[I_{n+1}] = E\left[E[I_{n+1} | s_{n+1} - s_n = z]\right] = 1 - \frac{p}{p+\lambda}$$

$$= \int_0^{+\infty} p e^{-pz} \times \left(1 - \frac{p}{p+\lambda}\right) dz = \frac{\lambda}{p+\lambda}$$

$\mathbb{P}\{N((s_n, s_{n+1}]) = 0 | s_{n+1} - s_n = z\}$ Since RAS does not depend on s_n

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Right, and because, you know, the times at which your web page changes and the times at which, you know, we access the web page, these two processes are independent. One can show that this probability actually equals $e^{-\lambda \tau}$, right? So this just follows from the fact that, you know, a Poisson random variable, right? Like, if you take this a b interval and if you ask what is the probability that this is 0. So because you have a Poisson random variable, this is $e^{-\lambda(b-a)}$, okay?

$$= \int_0^{+\infty} p e^{-pz} \times \left(1 - \mathbb{P}\{N((s_n, s_{n+1}]) = 0 | s_{n+1} - s_n = \tau\}\right) dz$$

$$= \int_0^{+\infty} p e^{-pz} (1 - e^{-\lambda \tau}) dz$$

$$\mathbb{P}\{N((a, b]) = 0\} = e^{-\lambda(b-a)}$$

So this is exactly what I have written over here, and this b minus a gets replaced by tau because of this conditioning over here.

The whiteboard shows the following derivation:

$$\begin{aligned} \text{We have } \mathbb{E}[I_{n+1} | s_{n+1} - s_n = z] &= \mathbb{P}\{I_{n+1} = 1 | s_{n+1} - s_n = z\} = 1 - \mathbb{P}\{I_{n+1} = 0\} \\ &= 1 - \frac{p}{p + \lambda} \\ &= \frac{\lambda}{p + \lambda} \\ &= \int_0^{+\infty} p e^{-pz} \times (1 - e^{-\lambda z}) dz \\ &= \int_0^{+\infty} p e^{-pz} (1 - e^{-\lambda z}) dz \end{aligned}$$

Since RHS does not depend on n , (I_n) is a sequence of IID Bernoulli random variables with mean $\frac{\lambda}{p + \lambda}$.

$\mathbb{P}\{N(a, b) = 0\}$

Just a minute, let me try this again because of this conditioning over here, right. So, that is why you end up with this e raised to minus lambda tau, and this just follows from this expression. So, now let me erase all these quantities over here, all right. So, this integral, by a simple calculation, can be seen to be 1 minus p over p plus lambda, which if you rearrange and do a bit of algebra can be seen to be lambda over p plus lambda. So, recall that this is the expression for the expected value of I_{n+1} .

$$\begin{aligned} &= \int_0^{+\infty} p e^{-pz} (1 - e^{-\lambda z}) dz \\ &= 1 - \frac{p}{p + \lambda} \\ &= \frac{\lambda}{p + \lambda} = \mathbb{E}[I_{n+1}] \end{aligned}$$

We have

$$E[I_{n+1} | \mathcal{F}_n] = P\{I_{n+1} = 1 | \mathcal{F}_n\} = 1 - P\{I_{n+1} = 0 | \mathcal{F}_n\}$$

$$E[I_{n+1}] = E\left[E[I_{n+1} | \mathcal{F}_n]\right] = 1 - \frac{p}{p+\lambda}$$

$$= \int_0^{\infty} p e^{-pz} \times \left(1 - \int_0^{\infty} P\{N(\mathcal{F}_n, \mathcal{F}_n) = 0 | \mathcal{F}_n = z\} dz\right) dz = \frac{\lambda}{p+\lambda}$$

Since RHS does not depend on n , (I_n) is a sequence of IID Bernoulli random variables with mean $\frac{\lambda}{p+\lambda}$.

$P\{N(a, b) = 0\} = e^{-\lambda(b-a)}$

Now, since the right-hand side over here, which I abbreviate as RHS, does not depend on n , right? One can conclude that the sequence I_n is actually a sequence of independent and identically distributed Bernoulli random variables with mean λ over $p + \lambda$, which is the expression that we had found over here. So, now what we are going to do is we are going to make use of this observation and come up with an algorithm to find λ . So, this is our goal now. So, let us see how we can go ahead and do that.

We have

$$E[I_{n+1}] = E\left[E[I_{n+1} | \mathcal{F}_n]\right] = \frac{\lambda}{p+\lambda}$$

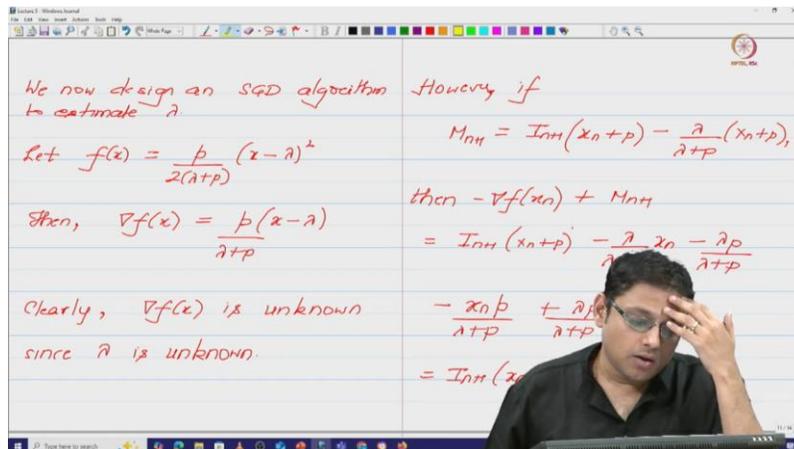
$$= \int_0^{\infty} p e^{-pz} \times \left(1 - \int_0^{\infty} P\{N(\mathcal{F}_n, \mathcal{F}_n) = 0 | \mathcal{F}_n = z\} dz\right) dz$$

Since RHS does not depend on n , (I_n) is a sequence of IID Bernoulli random variables with mean $\frac{\lambda}{p+\lambda}$.

So, now in order to come up with this algorithm, let me first define a function f . So, this function goes from the real line to the real line and is given by this definition over here. It is p over 2 times λ plus p times x minus λ the whole square.

$$f(x) = \frac{p}{2(\lambda + p)} (x - \lambda)^2$$

And so, how we came up with this function and so on I will talk about it, but at this point bear with me and let us say f is some \mathbb{R} to \mathbb{R} function given by this expression. So, if you look at $\text{grad } f$ of x , then you can see that this expression is basically p over λ plus p times x minus λ .



Now the expression for gradient of f of x is unknown right at any x since λ is unknown. So we do not know λ ; hence, the value of $\text{grad } f$ of x is unknown. If we define the noise sequence M_{n+1} using the expression on the right, I will tell you how this noise expression came about and so on and so forth, but bear with me for the time being. If we define the noise expression using the following formula, that is I_{n+1} times X_n plus P minus λ over λ plus P times X_n plus B . So, at this point you can just note that this I_{n+1} that you have over here, its expected value is written over here, and these two expressions are basically one and the same.

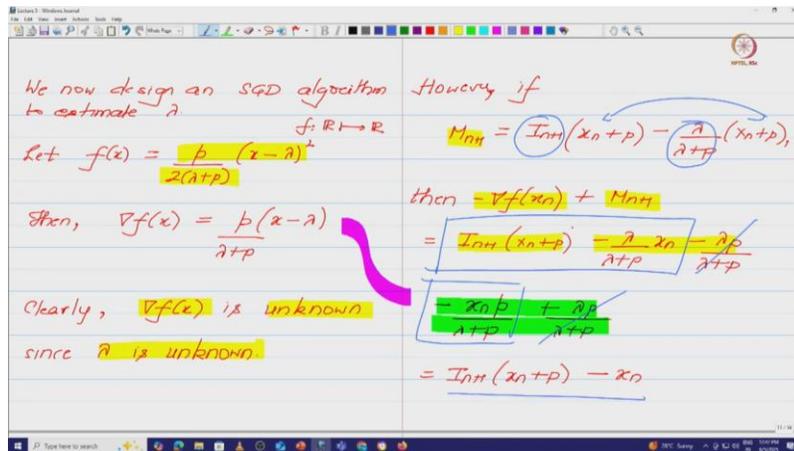
So, you can sort of see the nice structure that M_{n+1} has.

$$\nabla f(x) = \frac{p(x - \lambda)}{\lambda + P}$$

$$M_{n+1} = I_{n+1}(x_n + P) - \frac{\lambda}{\lambda + P} (X_n + P)$$

And now if you look at the expression for $-\text{grad } f$ of x_n plus M_{n+1} , then you can see that M_{n+1} from this above expression equals what is given over here. And the value of $-\text{grad } f$ of x_n from this equals this expression over here. Right, and you can

see that these two terms actually cancel off, and hence by simple algebra one can see that whatever remains—that is, this expression and this expression—if you combine them, you can see that we end up with this expression. So, at this point I am sure as a reader you would not know why we chose this f function, why we defined M_{n+1} to be in this form.



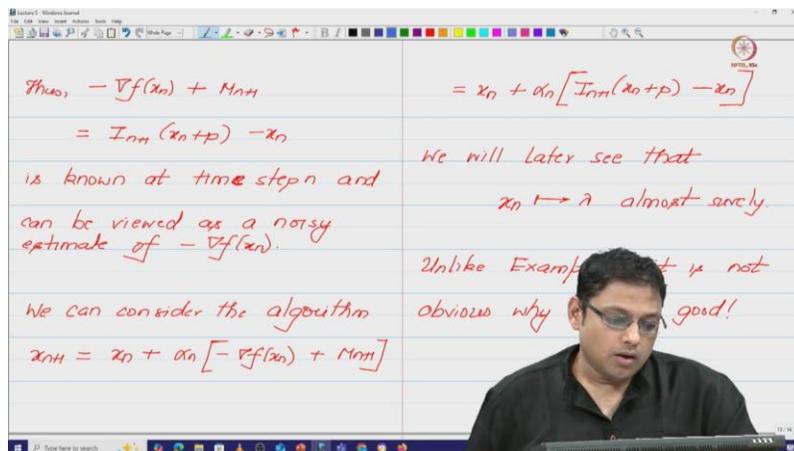
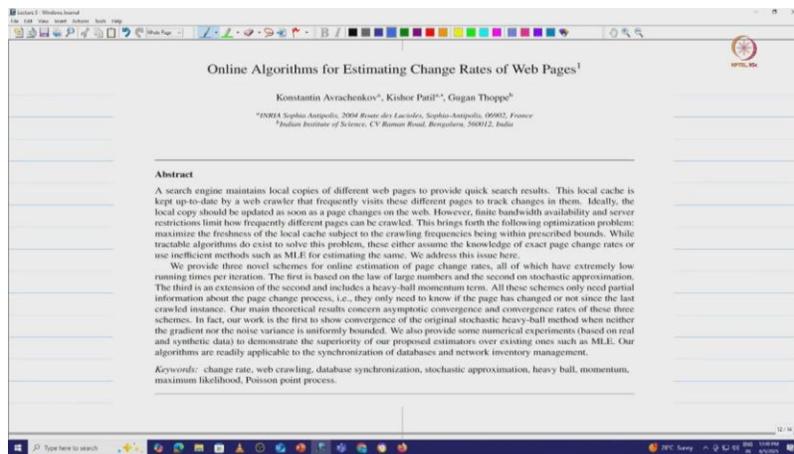
However, what you can observe is this expression for minus grad f of x_n plus m_{n+1} is what is given over here. And this expression can be computed at the time step n . It can be computed because at time step n , which in the real line corresponds to the true time instance S_{n+1} , we would know the value of I_{n+1} . And since we would have already computed X_n , we would also know X_n and P is the rate at which we access the webpage. So, this is also something that we know.

So, one can see that every term in this blue box is actually known. Hence, this expression is known, right? So, while grad of f of X_n is unknown because λ is unknown. The value of minus grad f of x_n plus m_{n+1} is known. In other words, while the required gradient is unknown, a noisy estimate of this gradient can be obtained by just looking at the values of I_{n+1} , x_n and p .

So, this is in some sense the advantage of working with this f and this noise variable. You know you can actually get hold of more details about this algorithm which I had the opportunity to work on as part of this paper with my collaborators Professor Konstantin Averachenkov and Kishore Patil. This is the name of the paper in which we had designed this algorithm and if you are interested you can go to my Google Scholar profile and you

know get hold of this paper and read the details further. So, at this point what we have is that while minus grad f of x_n is unknown because λ is unknown but minus grad f of x_n plus m_n plus 1 equals this quantity which is known at time step n and this can be viewed as a noisy estimate of minus grad f of x_n . So, in order to estimate λ we can consider now the following algorithm.

$$\begin{aligned}
 -\nabla f(x_n) + M_{n+1} &= I_{n+1}(X_n + P) - \frac{\lambda}{\lambda + P} x_n - \frac{\lambda P}{\lambda + P} - \frac{x_n P}{\lambda P} + \frac{\lambda P}{\lambda + P} \\
 &= I_{n+1}(x_n + P) - x_n
 \end{aligned}$$



So, let me go over this algorithm. This algorithm is $x_{n+1} = x_n + \alpha_n [I_{n+1}(x_n + P) - x_n]$. Indeed, we do not know grad f of x_n , but as we have pointed out here, the sum of minus grad f of x_n and m_n plus 1 is indeed known at the time step n , which corresponds to the true time instance S_{n+1} , right? So,

while this is not known, the sum is actually known, right? So, we can actually run this algorithm using just the values of I_n plus 1, right? And, you know, in that paper that I showed you in the previous slide, we have actually shown that X_n converges to λ , which is the quantity of interest, almost surely.

So, the almost surely part comes in here because X_n is a sequence of random variables, and, you know, when we talk of convergence of random variables, we have to use some appropriate quantification. And you will soon see that, you know, when we discuss the convergence of stochastic approximation algorithms, what do we mean by this almost sure convergence and how we can prove this. So, at this point, you know, you only have to note that, you know, this X_n update rule is actually nice. It is nice because, even though you do not know $\text{grad } f$ of x_n , it is making use of a noisy estimate of $\text{grad } f$ of x_n , which only involves quantities that you know. So, that is what is good about this algorithm on one hand.

In other words, you can actually implement this algorithm. On the other hand, you know, using the theory of stochastic approximation, we will see later that one can show that this X_n actually converges to λ . So, λ is the quantity of interest to us, and this algorithm actually converges there, and hence this will be a useful algorithm. Now, one thing that I have not spent too much time on is trying to understand, you know, what is good about this noise sequence or noise term M_n plus 1. I just gave you a hint that, you know, if you take the expectation of I_n plus 1, then you get this λ over λ plus p , something that I mentioned.

$$\begin{aligned} -\nabla f(x_n) + M_{n+1} &= I_{n+1}(x_n + P) - x_n \\ x_{n+1} &= x_n + \alpha_n [-\nabla f(x_n) + M_{n+1}] \\ &= x_n + \alpha_n [I_{n+1}(x_n + P) - x_n] \end{aligned}$$

$$M_{n+1} = -\nabla f(x_n) + M_{n+1}$$

$$= I_{n+1}(x_{n+p}) - x_n$$
 is known at time step n and can be viewed as a noisy estimate of $-\nabla f(x_n)$.

We can consider the algorithm

$$x_{n+1} = x_n + \alpha_n [-\nabla f(x_n) + M_{n+1}]$$

$$= x_n + \alpha_n [I_{n+1}(x_{n+p}) - x_n]$$

We will later see that $x_n \rightarrow a$ almost surely. Unlike Exam it is not obvious why it is good!



We now design an SGD algorithm to estimate a .

$$f: \mathbb{R} \rightarrow \mathbb{R}$$
 Let $f(x) = \frac{\beta}{2(\alpha+p)} (x-a)^2$

Then, $\nabla f(x) = \frac{\beta}{\alpha+p} (x-a)$

Clearly, $\nabla f(x)$ is unknown since a is unknown.

However if

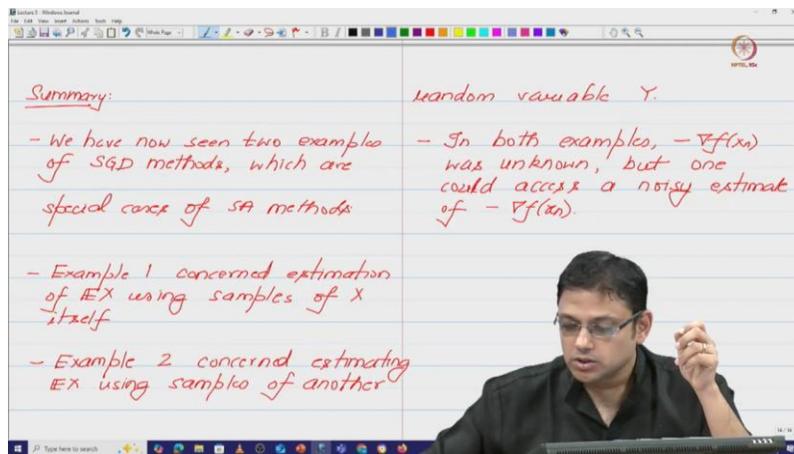
$$M_{n+1} = I_{n+1}(x_{n+p}) - \frac{\beta}{\alpha+p} (x_{n+p})$$
 then $-\nabla f(x_n) + M_{n+1}$

$$= I_{n+1}(x_{n+p}) - \frac{\beta}{\alpha+p} x_n = \frac{\beta}{\alpha+p} (x_{n+p} - x_n)$$

$$= \frac{\beta}{\alpha+p} (x_{n+p} - x_n)$$

$$= I_{n+1}(x_{n+p}) - x_n$$

And then this X_n plus P term is the same in both the first summand and the second summand. So, other than that, I have not told you, but you will soon see that this M_n plus 1 is a nice noise sequence—nice in the sense that you can apply a lot of existing mathematical theory to understand the behavior of this noise term M_n plus 1. So this is something that we will understand in future classes. So now let me finish this lecture 3 by summarizing what we have done so far. So far, we have seen two examples of SGD methods.



So I think I did not emphasize it. Even for example 2, the algorithm that we came up with is actually an SGD method—that is, stochastic gradient descent—and as I have mentioned in the first class, SGD methods are special cases of stochastic approximation methods. Now, we have looked at two examples. In example 1, we looked at the case of estimating the expected value of X using samples of the random variable—random vector X itself. In example 2, we looked at estimating the expectation of a random variable X .

We wanted to estimate this quantity λ , which, in some sense, the inverse of this was the expected value of the interarrival times—that is, $t_n + 1 - t_n$ —and we used this, I mean, we did this estimation using samples of another random variable y . In this case, the random variable y that we had access to were these in plus 1, i_1, i_2, i_3 , and so on. So, we made use of these values to estimate something about λ . And we also noted that in the two examples, the true gradient was inaccessible—it was unknown because it depended on quantities that were unknown. But one could access a noisy estimate of these negative gradients.

And because we could make use of, you know, these noisy estimates, we can actually run these SGD methods in practice. Even though we do not know these unknown quantities, in particular, we do not know these unknown gradients. We can actually run this algorithm, and in future lectures, we will see how we can analyze these algorithms. In particular, we will see how we can understand the convergence of these algorithms. That is one thing we will discuss in a future class. In the next class, we will also try to see an example of a stochastic approximation method that is not an SGD.

So, as I told you, SGD methods are a special subclass of stochastic approximation methods. However, the true power or potential of stochastic approximation lies in the fact that we can also view them beyond the standard SGD methods. Okay, with this, let me stop. Thank you, and namaste!

